

Particle Image Velocimetry



Setup

Light scattering particles are added to the flow. A laser beam The particle image is subdivided into small interrogation configurations cover a wide range of applications in gaseous (u,v) in this interrogation window is given by u=(1/M)(Δx/Δt) and liquid media.



Evaluation

th a short time interval ∆t. The scattered light is _particle image separation (∆x, ∆y) is determined by cross- Capturing and computing a sequence of images can provide onto two consecutive frames of a high resolution correlation and localization of the correlation peak. When M ra. Microscopic, endoscopic and macroscopic is the magnification of the camera the velocity components and $v = (1/M)(\Delta v/\Delta t)$.



inform ation about the temporal behavior of the flow



Stereo PIV

From the velocity field a range of spatial derivatives can be All three velocity components inside a two dimensional field A Tomographic PIV system with typically 2-4 car easurement into a full volume. Process is formed into a light sheet illuminating seeding particles windows. For each interrogation window the average derived such as vorticity, shear stress and turbulent energy. of view can be measured using a second camera and stereoscopic the flow m tomographic reconstruction of voxel intensities for each time imaging. After image calibration the three components of the wed by 3D3C-cr velocity vector can be derived from the two displacement projections. Scheimpflug lens arrangements keep all areas volumes. This allows for instantan three velocity components in a three dimensional measure of the image plane in focus volume (3D3C) visualizing the 3D flow structure.

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PIV is a non intrusive measurement technique used to obtain instantaneous velocity fields in a two dimensional region of gas or liquid flows.



Tomographic PIV